



SRC 2.0 – The Evolution of the SRC into Horizon Europe

*“An advanced SRC for Horizon Europe, which guides Europe towards a sustainable, highly-automated, flexible and economical viable space infrastructure, enhancing manifold commercial opportunities in space and on earth :
the new space ecosystem.”*

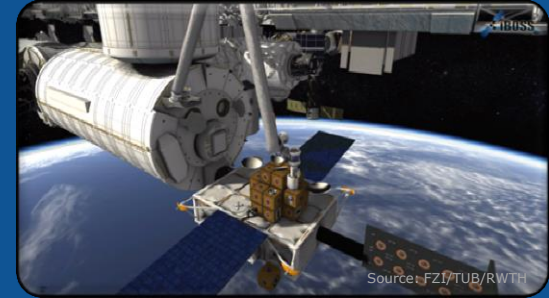
PSA PERASPERA

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Outline

- Scheme of the evolved SRC in Horizon Europe
- General objectives of the SRC
- Mission of the SRC
- Visionary wrap-up (videos)



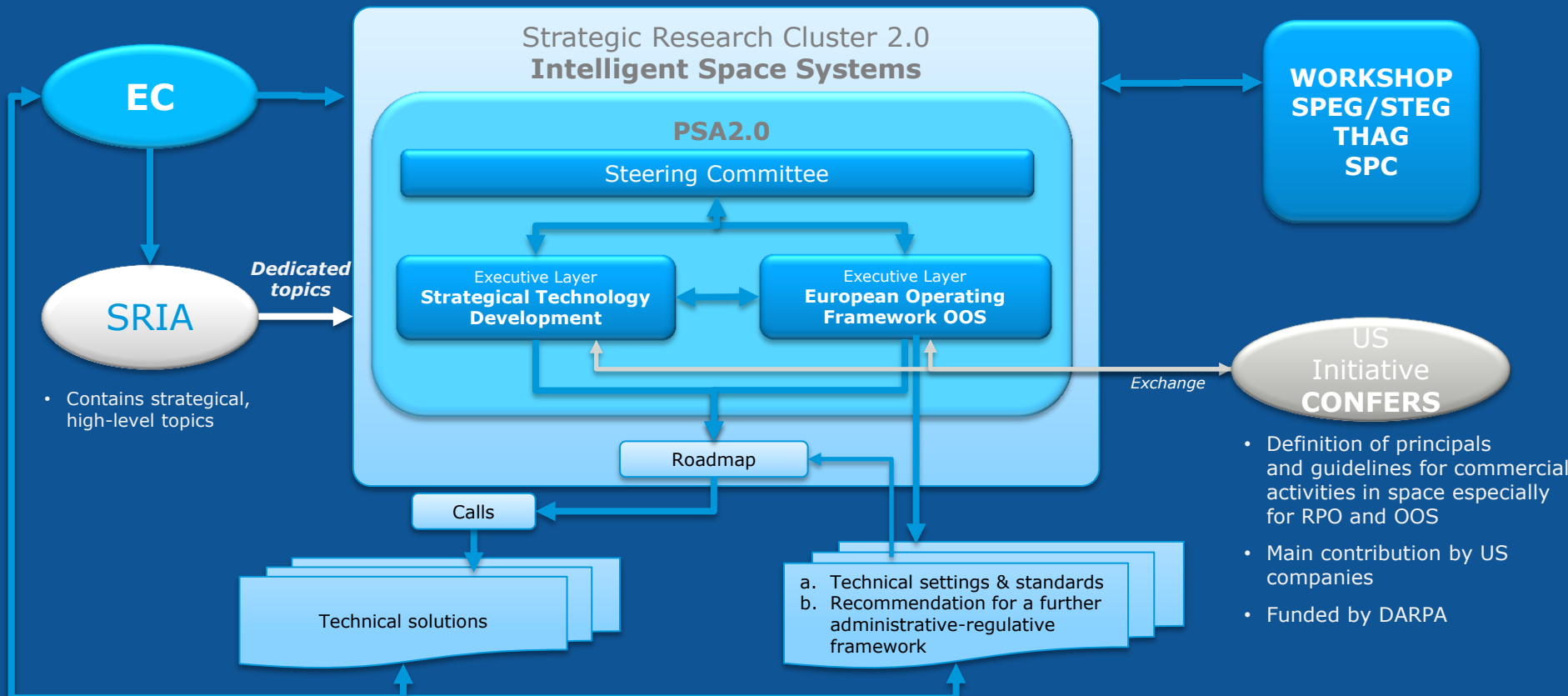


Identified improvements for PSA & SRC2.0

- PSA involvement opened to new actors
 - Associations (e.g. euRobotics, EUROSPACE, SME4SPACE, ESOA)
 - More interested and qualified member states
- Increased reflection of industry position, especially in the short and mid term
 - Definition of collaborative activities with associations
 - Higher number of and more efficient stakeholder consultations
 - Increased use of synergies with terrestrial sector
- More flexibility in roadmap/activities definition (disruptive approaches, competitions,..)
- Enhance exploitation of SRC developments/products
- Dealing with recommendations for law & decision makers



Proposed scheme of the evolved SRC in Horizon Europe





SRC2.0 Objectives

Demonstration

- **Demonstrate capabilities & business enablers**
 - represent a risk-taking, disruptive approach to enable new commercial opportunities in space (satisfying short-term and mid-to-long-term)
 - improve exploration capabilities by innovative technologies & concepts for all disciplines of robots

Strategical Roadmapping

- **Enable a paradigm shift** together with stakeholders towards a sustainable, highly-automated, flexible and economical viable space infrastructure, enhancing manifold commercial opportunities in space and on earth
- **Generate new market opportunities**
- **Enable business** in Space
- **Strengthen European industry and institutions**
- Setting **technology standards** and **define principles & guidelines** for commercialization of space
- **Protection of the space ecosystem**

Strengthen the European position in the space sector by applying

- *breakthrough disruptive technologies*
- *artificial intelligence*
- *digitalisation*
- *new industrial processes and innovative approaches for design production, AIT, logistics and operations*

How robotics will matter in space...

Classic monolithic system

Long
Time-to-Market

One-of-a-kind
approach

No Flexibility

High development
costs

high-effort
AIT

Space Debris



Demands of future Spacecraft

- Adjustable to customer's desires
- Adjustable to mission need
- Easy to maintain
- Shared common
- Resource-saving
- Debris-free
- Cost efficient
- Rapid Development
- Production on Demand
- Design-to-Production

cooperative/
robotic compatible
design

new production,
new logistics
and operations
philosophy



Mission of SRC2.0: Enabling industrialization and business in Space

„Develop building blocks independently from applications“

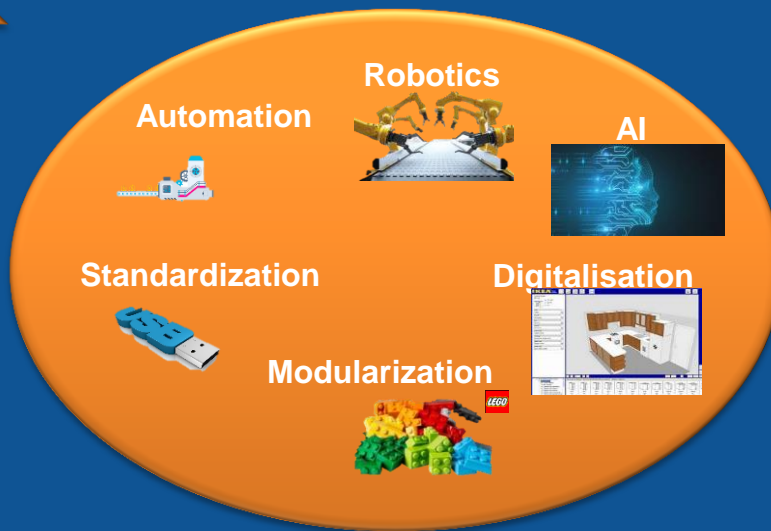


Long-term objective:
**Highly-automated,
flexible, sustainable
and economical
viable space
infrastructure**



“System Intelligence”

Adaptive/intelligent spacecraft



Mission-specific, non-flexible spacecraft



**Building Set/App Store
Paradigm**

- Introduces new commercial possibilities **“build your business”**
- Reduction of **mission costs** while keeping product/system diversity
- Increasing **flexibility**
- **Independent development** (platform/application)
- **Rapid development**, Rapid production and Rapid AIT
- Simplified **introduction of innovations**
- Digitalisation of building set supports **flexibility at customer level**



Expected evolution of space infrastructure

Short term

- Life extension
- Inspection
- Orbit change & debris removal

Mid term

- + Hosted payload/ IOD-V services
- + Exchange of components
- + Debris mitigation
- + Robotised deployment & assembly

Long term

- + Manufacturing in Space
- + Re-configuration
- + In-orbit Recycling
- + Logistics/assembly platforms
- +

Non-automated, non-flexible space infrastructure based on monolithic, individual design of spacecraft

Automated, flexible space infrastructure based on modular, adaptable design of spacecraft

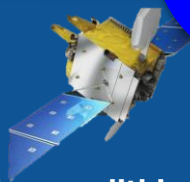
Terrestrial Robotics
building blocks/set methodology,
industrial processes and tools

AI

Big data, enhance system autonomy

Classic monolithic systems

Adaptive/intelligent systems





Expected evolution of planetary robotics

Short term

- + Rover autonomy extension
- + Rover mobility enhancement
- + Improved data fusion capabilities

Mid term

- + Long range autonomy
- + Access to difficult sites
- + Opportunistic science
- + Cooperative exploration

Long term

- + ISRU
- + Cooperative building assembly
- + Human base construction
- + Crews of robotic agents

Paradigm shift

limited autonomy rover, single-agent mission, limited operating range

Fully autonomous robot, flexible robotic agent, team of robots, Human-Robot cooperation

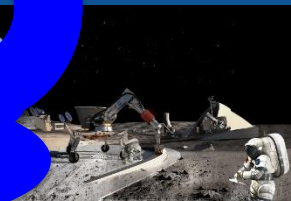


Terrestrial Robotics

Agriculture, Construction, Health, Mining, Rescue, Maritime, Nuclear

AI

Deep learning, Big Data





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International activities and trends

Short term

Mid term

Long term

Horizon Europe
SRC2.0 – Intelligent Space Systems

Horizon 2020
SRC – Space Robotics Technologies

trend visible



2020

2022

2024

2026

2028

2030

2032

2034

Table 1: Preliminary Roadmap for On-Orbit Assembly Ventures

	Phase			
	Crawl	Walk	Jog	Run
Goal	Human-in-the-loop on-orbit servicing and assembly 	Inter-vehicle on-orbit assembly (i.e., servicing) 	Intra-vehicle on-orbit assembly 	Space fleets for planetary exploration

2030

2032

2034



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Using synergies in Space & Terrestrial Sector

euRobotics



Spin-In/-Out
Coordination Actions
Building Blocks
Idea challenges
Competitions

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**Orbital
Track**



**Common
Track**



**Planetary
Track**









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Thank you for your attention!